

# CS 42I Lecture 12

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- ▶ **Compilation static languages, continued**
  - ▶ Compiling in context (main for optimization)
    - ▶ Assignment
    - ▶ Break statements
    - ▶ Short-circuit evaluation of boolean expressions
  - ▶ Switch statements
  - ▶ Arrays
  - ▶ Code optimization
- ▶ **Thursday's class: dynamic language execution via an example: the Sun HotSpot runtime system – tagged values; garbage collection**

# Notation

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- ▶  $[S]$  = compiled code for  $S$
- ▶  $[e]$  = compiled code for  $e$
- ▶ Use subscripts on brackets for additional arguments, e.g.  $[S]_L$  is compiled code for  $S$ , assuming  $S$  occurs within a switch statements labeled  $L$ .

## Assignment statements

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- ▶ Old scheme:  $[x=e] = \text{let } (l,t) = [e] \text{ in } l; x=t.$
- ▶ Can give poor results:  $[x=3] = t=3; x=t$   
 $[x=x+1] = t1=1; t2=x+t1; x=t2$
- ▶ Compile expressions in context of target location:  
 $[e]_x =$  code to calculate value of  $e$  *and*  
store it in  $x$ .  $[e]_x$  : instruction list
- ▶  $[x=e] = [e]_x$
- ▶  $[n]_x = \text{“}x=n\text{”}$
- ▶  $[y]_x = \text{“}x=y\text{”}$ , if  $y$  a different variable from  $x$ ;  $\epsilon$ , otherwise
- ▶  $[e1+e2]_x = \text{let } t = \text{new location in } [e1]_t; [e2]_x; x=t+x$

## break statements

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- ▶ break statement breaks from one level of switch or while. Cannot translate “break” without knowing context.
- ▶  $[S]_L$  = code for statement  $S$ , given that  $S$  occurs inside a switch or while statement, and  $L$  is the label just after that enclosing statement.

# Boolean expressions

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- ▶ Current scheme: boolean expressions evaluated like any other, placing value in a temporary location:

$$[e1 < e2] = \text{let } (l_1, t1) = [e1], (l_2, t2) = [e2], t = \text{newloc}() \\ \text{in } (l_1; l_2; t = t1 < t2, t)$$

$$[e1 \ \&\& \ e2] = \text{let } (l_1, t1) = [e1] \\ (l_2, t2) = [e2] \\ \text{in } (l_1; l_2; t = t1 \ \&\& \ t2, t)$$

$$[\text{if } e \ \text{then } S1 \ \text{else } S2] = \text{let } (l, t) = [e] \\ \text{in } (l; \text{CJUMP } t \ L1 \ L2; \dots)$$

- *What's wrong?*

# Boolean expressions w/ short-circuit evaluation

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- ▶ Improved scheme:

```
[e1 && e2] = let t = newlocation()
              I1 = [e1]t
              I2 = [e2]t
              L1, L2 = newlabel()
in (I1
    CJUMP t, L1, L2
    L1: I2
    L2:      , t)
```

- What's wrong now?

# Compiling boolean expressions in context

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- ▶ Get better code if boolean expression can jump to correct label as soon as possible
- ▶  $[e]_{L_t, L_f}$  = code that calculates  $e$  and jumps to  $L_t$  if it is true,  $L_f$  if it is false. The code does not save the value anywhere.

- ▶  $[\text{true}]_{L_t, L_f}$

$[e_1 < e_2]_{L_t, L_f}$

# Compiling boolean expressions in context

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- ▶  $[e1 \ \&\& \ e2]_{Lt,Lf}$

$[while \ e \ do \ S]$



# Compiling switch statement

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- ▶ Use “jump table” and address calculation

# Compiling object references

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- ▶ In expression  $e.t$ :
  - ▶ Type of  $e$  is known; call its class  $C$
  - ▶ Location of field  $t$  within  $C$  is known; say its offset is  $o$
  - ▶  $[e]$  will produce  $(l, t)$ , where  $t$  contains pointer to object
- ▶  $[e.t] = \text{let } (l, t) = [e]$   
     $t_l = \text{newlocation}()$   
    in  $(l; t_l = t + o, t_l)$
- ▶ Method calls  $e.t(\dots)$  more complicated – will discuss in a couple of weeks

## Compiling array references

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- ▶ Simple rule: If  $A$  has elements of type  $T$ , and if elements of type  $T$  occupy  $n$  bytes, then address of  $A[i]$  is address of  $A + i*n$ .
- ▶  $[A[e]] = \text{let } (l, t) = [e]$   
in  $(l$   
     $t1 = \&A$   
     $t2 = t*w$  ( $w$  size of  $A$ 's elements)  
     $t3 = t1+t2$   
     $t4 = \text{LOADIND } t3, \quad t4)$

# Compiling array references

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- ▶ Idea extends to multi-dimensional arrays.

# Machine-independent optimizations

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- ▶ Machine-independent optimization = optimizations that can be done at the level of IR – i.e. does not depend upon features of target machine such as registers, pipeline, special instructions
- ▶ E.g. “loop-invariant code motion”:

```
int A[100][100]
```

```
while (j<n) {  
    x = x + A[i][j]  
    j++;  
}
```

```
t1 = &A  
t2 = i*100  
t3 = t2+j  
t4 = t3*4  
t5 = t1+t4  
t6 = LOADIND t5  
x = x+t6  
j = j+1
```

# Machine-dependent optimizations

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- ▶ Machine-dependent optimization = optimizations that exploit features of target machine such as registers, pipeline, special instructions
  - ▶ Register allocation
  - ▶ Instruction selection
  - ▶ Instruction scheduling